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Description This website presents the principles of finite deformation continuum mechanics with many example applications to metals and incompressible viscoelastic materials (rubber). It can serve as lecture notes for a graduate level course in continuum mechanics for engineers interested in the subject.

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$dx(1) \cdot dx(2) = dx(1) dx(2) \cos \theta = dx(1) dx(2) (4.7-11)$ where θ is the angle between the deformed vectors as shown in Figure 4.3. If now we let θ , the angle measures the small change in the original right angle between $dx(1)$ and $dx(2)$ and also $\cos \theta = \cos 90^\circ + \sin 90^\circ \theta$ since θ is very small for infinitesimal deformations.

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