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Katsuhiko Ogata is a professor of engineering who was born in Tokyo , Japan ; on January 6 of 1925 . He earned a Bachelor degree in Mechanical Engineering from the University of Tokyo in 1947. After receiving his degree, he spent three years as a research assistant at the Scientific Research Institute in Tokyo , followed by two years of ...

~~Katsuhiko Ogata (Author of Modern Control Engineering)~~

A comprehensive, senior-level textbook for control engineering. Ogata's Modern Control Engineering, 5/e, offers the comprehensive coverage of continuous-time control systems that all senior students must have, including frequency response approach, root-locus approach, and state-space approach to analysis and design of control systems.

For senior or graduate-level students taking a first course in Control Theory (in departments of Mechanical, Electrical, Aerospace, and Chemical Engineering). A comprehensive, senior-level textbook for control engineering. Ogata's Modern Control Engineering, 5/e , offers the comprehensive coverage of continuous-time control systems that all senior students must have, including frequency response approach, root-locus approach, and state-space approach to analysis and design of control systems. The text provides a gradual development of control theory, shows how to solve all computational problems with MATLAB, and avoids highly mathematical arguments. A wealth of examples and worked problems are featured throughout the text. The new edition includes improved coverage of Root-Locus Analysis (Chapter 6) and Frequency-Response Analysis (Chapter 8). The author has also updated and revised many of the worked examples and end-of-chapter problems. This text is ideal for control systems engineers.

For junior-level courses in System Dynamics, offered in Mechanical Engineering and Aerospace Engineering departments. This text presents students with the basic theory and practice of system dynamics. It introduces the modeling of dynamic systems and response analysis of these systems, with an introduction to the analysis and design of control systems.

A concise, engaging, practical overview of children's literature that keeps the focus on the books children read. This brief introduction to children's literature genres leaves time to actually read children's books. Written on the assumption that the focus of a children's literature course should be on the actual books that children read, the authors first wrote this book in 1996 as a "textbook for people who don't like children's literature textbooks." Today it serves as an overview to shed light on the essentials of children's literature and how to use it effectively with young readers, from PreK to 8th grade. The authors use an enjoyable, conversational style to achieve their goal of providing a practical overview of children's books that offers a framework and background information, while keeping the spotlight on the books themselves.

Written as a companion volume to the author's Solving Control Engineering Problems with

MATLAB, this indispensable guide illustrates the power of MATLAB as a tool for synthesizing control systems, emphasizing pole placement, and optimal systems design.

Notable author Katsuhiko Ogata presents the only new book available to discuss, in sufficient detail, the details of MATLAB® materials needed to solve many analysis and design problems associated with control systems. Complements a large number of examples with in-depth explanations, encouraging complete understanding of the MATLAB approach to solving problems. Distills the large volume of MATLAB information available to focus on those materials needed to study analysis and design problems of deterministic, continuous-time control systems. Covers conventional control systems such as transient response, root locus, frequency response analyses and designs; analysis and design problems associated with state space formulation of control systems; and useful MATLAB approaches to solve optimization problems. A useful self-study guide for practicing control engineers.

A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The text features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

The book blends readability and accessibility common to undergraduate control systems texts with the mathematical rigor necessary to form a solid theoretical foundation. Appendices cover linear algebra and provide a Matlab overview and files. The reviewers pointed out that this is an ambitious project but one that will pay off because of the lack of good up-to-date textbooks in the area.

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